Using formulae for the associated LeGendre polynomial determine the rotational transition moment for the transition from J = 0 to J = 1. This derives from the general selection rule $\Delta J = 1$ or -1 and $\Delta M = 0$.

Using formulae for the associated LeGendre polynomial determine the rotational transition moment for the transition from J = 0 to J = 1. This derives from the general selection rule $\Delta J = 1$ and $\Delta M = 0$.

Solution: the general solution for rotation states is

$$Y_{JM}(\theta,\phi) = \sqrt{\frac{(2J+1)(J-M)!}{4\pi(J+M)!}} P_{JM}(\cos\theta)e^{iM\phi}$$

For J = 0, M = 0

$$Y_{00}(\theta,\phi) = \sqrt{\frac{1}{4\pi}}$$

For J = 1, M = 0

$$Y_{10}(\theta,\phi) = \sqrt{\frac{(2+1)(1)!}{4\pi(1)!}} P_{10}(\cos\theta) = \sqrt{\frac{3}{4\pi}}\cos\theta$$

Using formulae for the associated LeGendre polynomial determine the rotational transition moment for the transition from J = 0 to J = 1. This derives from the general selection rule $\Delta J = 1$ and $\Delta M = 0$.

The transition moment is:

$$M_{01} = \int_{0}^{2\pi} d\phi \int_{-1}^{1} Y_{10}(\theta, \phi) \mu_z x Y_{00}(\theta, \phi) dx$$

where we make the substitution $x = \cos\theta$.

$$M_{01} = 2\pi \int_{-1}^{1} \sqrt{\frac{3}{4\pi}} x \mu_z x \sqrt{\frac{1}{4\pi}} dx$$

Using formulae for the associated LeGendre polynomial determine the rotational transition moment for the transition from J = 0 to J = 1. This derives from the general selection rule $\Delta J = 1$ and $\Delta M = 0$.

Consolidating terms we find that the transition dipole moment is

$$M_{01} = \sqrt{\frac{3}{4}} \mu_z \int_{-1}^{1} x^2 dx = \sqrt{\frac{3}{4}} \mu_z \left(\frac{1}{3} - \frac{-1}{3}\right) = \frac{\mu_z}{\sqrt{3}}$$