## Quantum Chemistry

Lecture 5<br>Group Theory

Matrix Representation
Cartesian Basis
Reducible and Irreducible Representations

NC State University

## Matrix representation of a basis

The basis is comprised by the labels attached to objects. For molecules the objects can be:

1. Atoms
2. Coordinates
3. Orbitals
4. Bonds
5. Angles

The number of basis functions or labels is called the dimension.

For example, when considering molecular motions we Can assign coordinates $x, y$ and $z$ to each atom. There are three coordinates for N atoms to give a total dimension of 3 N .

## Matrix representation of the rotation operator

$$
\begin{gathered}
\left(\begin{array}{l}
\mathrm{x}_{\mathrm{f}} \\
\mathrm{y}_{\mathrm{f}} \\
\mathrm{z}_{\mathrm{f}}
\end{array}\right)=\left(\begin{array}{ccc}
\cos \alpha & \sin \alpha & 0 \\
-\sin \alpha & \cos \alpha & 0 \\
0 & 0 & 1
\end{array}\right)\left(\begin{array}{l}
\mathrm{x}_{\mathrm{i}} \\
\mathrm{y}_{\mathrm{i}} \\
\mathrm{z}_{\mathrm{i}}
\end{array}\right) \\
\left(\begin{array}{l}
\mathrm{x}_{\mathrm{f}} \\
\mathrm{y}_{\mathrm{f}} \\
\mathrm{z}_{\mathrm{f}}
\end{array}\right)=\mathrm{C}_{3}\left(\begin{array}{l}
\mathrm{x}_{\mathrm{i}} \\
\mathrm{y}_{\mathrm{i}} \\
\mathrm{z}_{\mathrm{i}}
\end{array}\right)=\left(\begin{array}{ccc}
-1 / 2 & \sqrt{3} / 2 & 0 \\
-\sqrt{3} / 2 & -1 / 2 & 0 \\
0 & 0 & 1
\end{array}\right)\left(\begin{array}{l}
\mathrm{x}_{\mathrm{i}} \\
\mathrm{y}_{\mathrm{i}} \\
\mathrm{z}_{\mathrm{i}}
\end{array}\right)
\end{gathered}
$$

## Matrix representation of the reflection operators

$$
\begin{aligned}
& \left(\begin{array}{l}
x_{f} \\
y_{f} \\
z_{f}
\end{array}\right)=\sigma_{v, y z}\left(\begin{array}{l}
x_{i} \\
y_{i} \\
z_{i}
\end{array}\right)=\left(\begin{array}{ccc}
-1 & 0 & 0 \\
0 & 1 & 0 \\
0 & 0 & 1
\end{array}\right)\left(\begin{array}{l}
x_{i} \\
y_{i} \\
z_{i}
\end{array}\right) \\
& \left(\begin{array}{l}
x_{f} \\
y_{f} \\
z_{f}
\end{array}\right)=\sigma_{V, x z}\left(\begin{array}{l}
x_{i} \\
y_{i} \\
z_{i}
\end{array}\right)=\left(\begin{array}{ccc}
1 & 0 & 0 \\
0 & -1 & 0 \\
0 & 0 & 1
\end{array}\right)\left(\begin{array}{l}
x_{i} \\
y_{i} \\
z_{i}
\end{array}\right) \\
& \left(\begin{array}{l}
x_{f} \\
y_{f} \\
z_{f}
\end{array}\right)=\sigma_{v, x y}\left(\begin{array}{l}
x_{i} \\
y_{i} \\
z_{i}
\end{array}\right)=\left(\begin{array}{ccc}
1 & 0 & 0 \\
0 & 1 & 0 \\
0 & 0 & -1
\end{array}\right)\left(\begin{array}{l}
x_{i} \\
y_{i} \\
z_{i}
\end{array}\right)
\end{aligned}
$$

## Matrix representation of the inversion operator

$$
\left(\begin{array}{l}
\mathrm{x}_{\mathrm{f}} \\
\mathrm{y}_{\mathrm{f}} \\
\mathrm{z}_{\mathrm{f}}
\end{array}\right)=i\left(\begin{array}{l}
\mathrm{x}_{\mathrm{i}} \\
\mathrm{y}_{\mathrm{i}} \\
\mathrm{z}_{\mathrm{i}}
\end{array}\right)=\left(\begin{array}{ccc}
-1 & 0 & 0 \\
0 & -1 & 0 \\
0 & 0 & -1
\end{array}\right)\left(\begin{array}{l}
\mathrm{x}_{\mathrm{i}} \\
\mathrm{y}_{\mathrm{i}} \\
z_{\mathrm{i}}
\end{array}\right)
$$

## Example: Motions of $\mathrm{H}_{2} \mathrm{O}$

The basis vectors are shown for the three atoms of water. Also shown is the result of the $\mathrm{C}_{2}$ rotation:


If we examine the oxygen atom the rotation matrix can be formulated as:

$$
\left[\begin{array}{l}
\mathrm{x}_{\mathrm{j}} \\
\mathrm{y}_{\mathrm{j}} \\
\mathrm{z}_{\mathrm{j}}
\end{array}\right]=\left[\begin{array}{ccc}
-1 & 0 & 0 \\
0 & -1 & 0 \\
0 & 0 & 1
\end{array}\right]\left[\begin{array}{l}
\mathrm{x}_{\mathrm{i}} \\
\mathrm{y}_{\mathrm{i}} \\
\mathrm{z}_{\mathrm{i}}
\end{array}\right]
$$

## Motions of $\mathrm{H}_{2} \mathrm{O}$

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\left[\begin{array}{l}
\mathrm{x}_{\mathrm{j}} \\
\mathrm{y}_{\mathrm{j}} \\
\mathrm{z}_{\mathrm{j}}
\end{array}\right]=\left[\begin{array}{ccc}
-1 & 0 & 0 \\
0 & -1 & 0 \\
0 & 0 & 1
\end{array}\right]\left[\begin{array}{l}
\mathrm{x}_{\mathrm{i}} \\
\mathrm{y}_{\mathrm{i}} \\
\mathrm{z}_{\mathrm{i}}
\end{array}\right]
$$

The trace of this matrix is the sum of the diagonal elements.

## Motions of $\mathrm{H}_{2} \mathrm{O}$

Since there are atoms the full matrix for $\mathrm{H}_{2} \mathrm{O}$ is a $9 \times 9$ :

$$
\mathrm{C}_{2}\left(\begin{array}{l}
x_{1} \\
y_{1} \\
z_{1} \\
x_{2} \\
y_{2} \\
z_{2} \\
x_{3} \\
y_{3} \\
z_{3}
\end{array}\right)=\left(\begin{array}{ccc:cccccc}
-1 & 0 & 0 \\
0 & -1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
0 & 0 & +1 & 0 & 0 & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & 0 & -1 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & 0 & 0 & -1 & 0 \\
0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & +1 \\
0 & 0 & 0 & -1 & 0 & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & -1 & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & +1 & 0 & 0 & 0
\end{array}\right)\left(\begin{array}{l}
x_{1} \\
y_{1} \\
z_{1} \\
x_{2} \\
y_{2} \\
z_{2} \\
x_{3} \\
y_{3} \\
z_{3}
\end{array}\right)
$$

The hydrogen atoms are not on the diagonal since the atoms themselves are moved as a result of the $\mathrm{C}_{2}$ rotation.

The trace of this matrix is -1 . This is also called the character.

## Motions of $\mathrm{H}_{2} \mathrm{O}$

We can consider also the result of the $\sigma v$ mirror plane, which is also a $9 \times 9$ :

$$
\sigma\left(\begin{array}{l}
x_{1} \\
y_{1} \\
z_{1} \\
x_{2} \\
y_{2} \\
z_{2} \\
x_{3} \\
y_{3} \\
z_{3}
\end{array}\right)=\left(\begin{array}{ccccccccc}
-1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
0 & +1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
0 & 0 & +1 & 0 & 0 & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & -1 & 0 & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & +1 & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & +1 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & 0 & -1 & 0 & 0 \\
x_{1} \\
y_{1} \\
z_{1} \\
x_{2} \\
0 & 0 & 0 & 0 & 0 & 0 & 0 & +1 & 0 \\
y_{2} \\
y_{2} \\
z_{2} \\
x_{3} \\
y_{3} \\
z_{3}
\end{array}\right)
$$

None of the atoms are moved by the symmetry operation so all of the submatrices representing the vectors lie along the diagonal. For this operation the trace (also known as the character) is +3 .

## Conclusions for symmetry operations

We can conclude with 2 general rules:

1. Only those atoms, which remain in the place following an operation can contribute to the trace.
2. Each atom contributes the same samount to the trace since all of the atoms have the same $3 \times 3$ matrix.

Using these principles we can see that $\sigma_{v}$ ' has a character of +1 .
The identity always has a character equal to the number of basis functions. Here $\mathrm{E}=9$.

Using the character of the 4 symmetry operations of the $\mathrm{C}_{2 \mathrm{v}}$ point group we can construct a representation $\Gamma$.

## Reducible and irreducible representations

We call the representation $\Gamma$ a reducible representation. Here we write the reducible representation as:

| $\mathrm{C}_{2 \mathrm{v}}$ | E | $\mathrm{C}_{2}$ | $\sigma_{\mathrm{v}}(\mathrm{xz})$ | $\sigma_{\mathrm{v}}{ }^{\prime}(\mathrm{yz})$ |
| :---: | :---: | :---: | :---: | :---: |
| $\Gamma$ | 9 | -1 | 3 | 1 |

The irreducible representations form the basis of the point group in the same way that the vectors along $x, y$ and $z$ form the basis for three dimensional space.
$\mathrm{H}_{2} \mathrm{O}$ belongs the point group $\mathrm{C}_{2 v}$. In this point group There are 4 irreducible representations, $A_{1}, B_{1}, A_{2}, B_{2}$. The decomposition of the reducible representation is a Unique determination of the irreducible reps (or irreps)z spanned by $\Gamma$.

